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Title: **REACTIVE POWER MANAGEMENT IN ISLANDED MICROGRID-PROPORTIONAL POWER SHARING IN HIERARCHICAL BY USING FUZZY LOGIC CONTROL**

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## REACTIVE POWER MANAGEMENT IN ISLANDED MICROGRID- PROPORTIONAL POWER SHARING IN HIERARCHICAL BY USING FUZZY LOGIC CONTROL

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**Abstract:** A Microgrid (MG) is a neighbourhood energy system comprising of various energy sources (e.g., wind turbine or sun based boards among others), energy stockpiling units, and loads that work associated with the principle electrical grid or self-tuning. MGs give adaptability, diminish the fundamental power network reliance, and add to changing substantial incorporated generation worldview to neighborhood and conveyed generation. Be that as it may, such energy systems require complex administration, propelled control, and streamlining. Besides, the force hardware converters must be utilized to right energy transformation and be interconnected through basic control structure is essential. Established hang control system is regularly actualized in MG. It permits right operation of parallel voltage source converters in grid association, as well as islanded method of operation. In any case, it requires complex power administration calculations, particularly in islanded MGs, which adjust the system and enhances dependability. The novel reactive power sharing calculation is produced, which takes into account the converters parameters as evident force limit and most extreme active power. The created arrangement is checked in reproduction what's more, contrasted and other known reactive power control strategies.

**Keywords:** Renewable Energy Sources (RES), Microgrid (MG), Equivalent Reactive Power Sharing (ERPS).

### I. INTRODUCTION

Microgrid (MG) is a different system that produces what's more, stockpiles electrical energy, which comprises of renewable energy sources (RES), nearby loads, and energy stockpiling taking into account batteries or super capacitors. It is intrinsic part of present day and well known smart grids which incorporate moreover clever structures, electrical auto stations, and so forth. All RES are utilizing power devices (e.g., converters), which number fundamentally expanding and costs

diminishing in extent 1%–5% consistently. RES are generally associated with the network and numerous establishments cause the parallel operation of RES near each other. This is one of motivations to future change of the traditional structure of electrical power systems, toward new arrangement containing distributed generation, energy stockpiling, security and control innovations, and enhancing their exhibitions. MG is profoundly cutting-angle system from control and correspondence perspective. It

needs to oversee power for nearby loads as well as control all converters with high proficiency and exactness, particularly when MG works as islanded system. Islanding method of operation give the uninterruptible power supply for neighborhood loads amid network deficiencies. The exhibitions of islanded MG are determined. With expanding number of RES applications, working parallel, near each other (few km) and with created islanded method of operation, the MGs are gotten to be flawless answer for RES combination. Major calculations of air conditioning MGs, depicted, depend on master–slave control or progressive load control. The principal arrangement incorporates one and only converter with voltage control circle (VCL), working as an expert, and others working in current control circle (CCL)— slaves. The created force is controlled by sources with CCL and the voltage adequacy and recurrence is keeping in point of common coupling (PCC) by expert unit. Load of this arrangement is no plausibility to interface other VCL sources to MG, which are the most famous and utilized RES arrangements. The second control arrangement, called load control, incorporates numerous VCL sources and gives probability to a wide range of RES interconnection. Droop control depends on active and reactive power identified with voltage frequency and adequacy load on coupled impedances. Lamentably, traditional load control technique with relative hang coefficients does not gives appropriate reactive power sharing between converters associated with regular air

conditioning transport. In established methodology, the equivalent reactive power sharing (ERPS) can be acquired just when active powers are equivalent and hang coefficients are well picked as shown in Fig.1. At the point when active powers are changing, the reactive power sharing can't be controlled creating over-load or reactive power flow between converters. Also, the vital issue in load control is static exchange off between voltage directions what's more, reactive power. For expanding reactive power, the voltage load on converter's output impedance likewise increment, what may bring about over voltage. Keeping in mind the end goal to give fitting power sharing and minimize the danger of converter harm the numerous extra viewpoints (e.g., ostensible clear power, Momentary active power, ostensible voltage of converter) have to be considered in control system. There are just few papers portraying reactive power sharing between parallel working converters in islanded air conditioning MGs. The specialists concentrated on ERPS between all RES as a rule controlled by MG focal control unit or executed as virtual impedances. From the other hand, looks into consider responsive force partaking so as to upgrade transmission power misfortunes by fitting streamlining calculation (e.g., molecule swarm improvement), which can be disregarded in MGs, thus the short separations and the line impedances are low. In any case, calculations portrayed in writing are not considering capacities of single RES, which have restricted clear power. On the off chance that active power,

normally computed from maximum power point tracking (MPPT) calculations, get practically ostensible evident converter restrain the equivalent power sharing calculations can't be utilized, in light of the fact that the over-load can happen, what prompts harm or rejection from operation of RES unit.

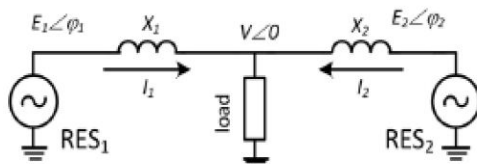


Fig. 1. Equivalent circuit of parallel connected VSIs.

## II. CLASSICAL DROOP CONTROL

At the point when no less than two RES are associated through vitality converters to the MG, the hang control strategy is regularly connected, what gives the right parallel operation of voltage source inverters (VSI). The equal circuit of two converters associated with normal air conditioning MG transport can be introduced by Fig. 2.

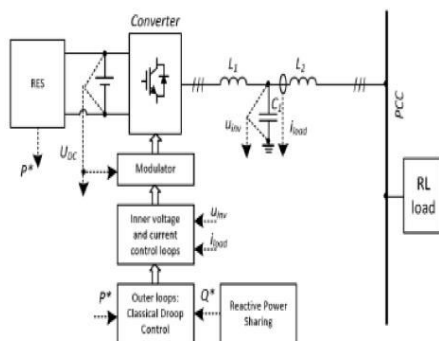


Fig. 2. Block scheme of control structure for one of the converters in islanded MG.

$P^*$  and  $Q^*$  are the active and reactive power referenced qualities, and  $G_p(s)$  and  $G_q(s)$  are comparing exchange capacities.

Commonly in traditional hang control  $G_p(s)$  and  $G_q(s)$  are corresponding (steady) load coefficients. It has happened, at the point when MG excludes any energy stockpiling and absolute load can't retain all out infused power. Piece plans of  $P-\omega$  and  $Q-E$  control circles is introduced in Fig. 3.

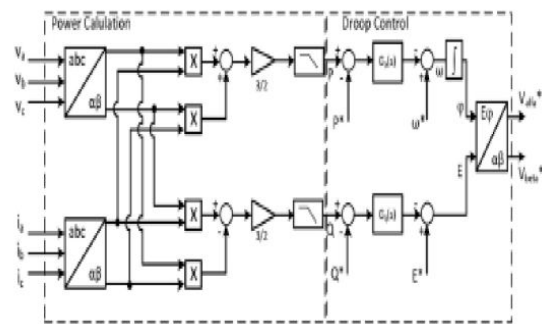


Fig. 3. Block scheme of classical droop control.

## III. PROPORTIONAL REACTIVE POWER SHARING

**A. Development of PRPS Algorithm** With a specific end goal to oversee reactive power in islanded alternating current MG the prompt active power and ostensible clear power of every converter must contemplate. In view of Fryze power hypothesis that power can be spoken to by orthogonal vectors, which lengths are active and reactive power and their vector whole is equivalent to the clear power. The reactive power limit for every converter can be figured

$$Q_{max} = \sqrt{S_N^2 - P^2} \quad (1)$$

Where  $Q_{max}$  is the greatest of conceivable converter's reactive power,  $S_N$  is the ostensible obvious power of converter;  $P$  is

the quick active power of converter. In this paper the symphonious (twisting) power is disregarding subsequent to just resistive inductive burden is considered. This connection for a few converters with various conceivable ostensible obvious powers and equivalent reactive powers (three converters in this case) can be deciphered graphically. In power adjusted system the vector total of converter's clear powers is equivalent to stack evident power paying little minds to the power administration technique, be that as it may, the logarithmic entirety of clear powers is distinctive for every control methodology. As an outcome, there is conceivable circumstance that aggregate of converter's clear powers are higher than the interest, which may lead to converters working with most extreme evident power. Moreover, if control need is keeping most extreme power, the over-load of converter can happen, as it is appeared for converter 1, what is not satisfactory, in light of the fact that it cause incapacitate or harm of this gadget. Keeping in mind the end goal to enhance the reactive power administration and keeping complete produced obvious power underneath most extreme level for whatever length of time that conceivable, the proposed reactive control calculation is keeping connection  $S_L/S_k$  on the most elevated amount. It will permit better misuse of every RES in entire MG, what can expand conceivable to active power generation of every converter without coming to of evident power limit. At the

point when converters are working with evident powers much lower than ostensible parameters, the above connection is equivalent one also; reactive power is sharing corresponding to active power of every converter. Sadly, this circumstance is one and only of conceivable case and the constraints of converters must be considered in reactive sharing control calculation so as to maintain a strategic distance from over-burdens

$$Q_{uk} = \frac{Q_L}{P_L} P_k \quad (2)$$

where,  $Q_{uk}$ , computed reactive power esteem for boundless case;  $Q_L$ , all out responsive force request;  $P_L$ , all out active power;  $P_k$ , active power of "k" converter;  $Q_k$ , reactive power of k converter;  $S_k$ , obvious power of k converter; and  $S_{Nk}$ , ostensible obvious power of k converter. Taking and portrayed investigation of reactive power sharing novel control calculation was produced. The flowchart of the calculation is appeared in Fig. 4. In single phase system parameters are spared in K-components tables, where K—number of converters,  $P[K]$ —measured active powers,  $S_N[K]$ —ostensible obvious forces. Moreover, points of confinement of reactive powers for every converter  $Q_{maxk}$ , and additionally add up to active power  $P_L$  are figured

$$P_L = \sum_k P_k. \quad (3)$$

When the following phase, the helper parameter  $Q_{sum}$ , characterized as a whole

of reference reactive powers of all restricted and boundless converters, is contrasted and load reactive power. This parameter permits checking if responsive force equalization is held. At the point when  $Q_{sum}$ , as a consequence of stages 3–5 portrayed beneath is distinctive than aggregate responsive force  $Q_L$ , then calculation is going to stage 3, generally the stage 6 followed and last referenced estimations of responsive force  $Q_k^*$  are characterized for every converter. In phases 3–5 the fundamental computation procedure of the reference qualities is executed. Firstly, the reactive power values relative to active powers are computed (phase 3). The proportionality variable is made out of parameters  $P_{rest}$  and  $Q_{rest}$ , which are complete active and reactive power  $P_L$  and  $Q_L$  in boundless case, else they are littler by barring all dynamic what's more, and reactive powers of constrained converters (stage 5). Next, the impediment is checked (stage 4) and the reference worth is set to greatest or to relative. Contingent upon the outcome, helper parameters  $Q_{lim}$ ,  $P_{lim}$  or  $Q_{unl}$ ,  $P_{unl}$  are ascertained, which are aggregates of active and reactive power of converters working with greatest obvious force or underneath it correspondingly (stage 4). At that point after all  $K$  cycles, the parameters  $P_{rest}Q_{rest}$ ,  $Q_{sum}$  are figured and the calculation is retreating to stage 2, where the condition (10) is checked, as said above.

**B. Implementation of Developed Algorithm** For more broad MG (e.g., number of sources  $K > 10$ ), the figuring of definite reference values in one basic control unit [e.g., optional control unit (SCU)]

might be long and not be conceivable, particularly if computations in SCU must be done in one converter exchanging period (typically 100–500  $\mu s$ ).

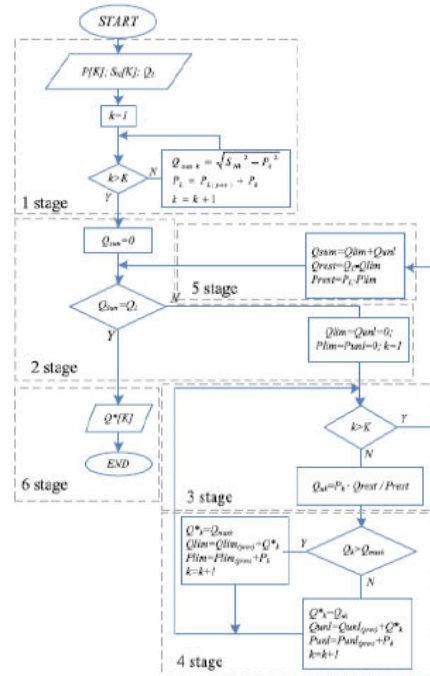


Fig. 4. Block diagram of developed reactive power sharing algorithm.

Thus, in view of Fig. 4 the calculation can be splitted between all power control units (PCU) containing inward control circles what's more, SCU, which is for the most part in charge of repaying the voltage abundance and frequency deviation brought about by load control in PCU. Thus, the time computation in SCU might be decreased enhancing control active and transient time. Proposed usage of exhibited calculation permits executing numerous forms parallel in PCUs. The square plan of proposed control calculation executed in PCUs and SCU is appeared in Fig. 6. The calculation ascertains the reactive power limit (7) and corresponding reactive power esteem for

boundless cases (8) in each PCU freely. Besides, the helper parameters  $P_{sk}$ ,  $Q_{sk}$  are characterized (11), (12), in view of genuine reactive power reference esteem  $Q^*$ . Keeping in mind the end goal to satisfy condition (10) the extra estimation of reactive power  $Q_k$  must be included to estimation of boundless case  $Q_{uk}$  for each boundless converter. It is characterized by (13) and relies on upon entirety of active power of constrained converters  $P_{sL}$ , entirety of reactive power of restricted converters  $Q_{sL}$ , all out active and real powers  $P_L$  and  $Q_L$ , reactive power estimation of boundless case  $Q_{uk}$  and helper parameter  $Q_{sk}$ . The parameter  $Q_k$  can be diverse for every  $k$ , relatively to  $P_k$ , subsequently the PRPS for boundless converters is still fulfilled.

$$P_{S_k} = \begin{cases} P_k & \text{if } Q^*_k = Q_{max k} \\ 0 & \text{otherwise} \end{cases} \quad (4)$$

$$Q_{S_k} = \begin{cases} Q^*_k & \text{if } Q^*_k = Q_{max k} \\ 0 & \text{otherwise} \end{cases} \quad (5)$$

### C. PRPS Algorithm in Real Distributed Control System

In real distributed control system, a few distinct processors in PCUs and remote SCU need to share their computational results. Any synchronization amongst PCUs and SCU are not required in introduced arrangement. The deferral can be disregarded for present day correspondence system with transmission speed in scope of megabit every second (Mb/s) and just few km separations between control units in all MG components. Accordingly, utilization of appropriated control system for created calculation was proposed (Fig. 5) what can take into consideration higher computational rate. One of the conceivable correspondence issues is misfortune information in a few periods.

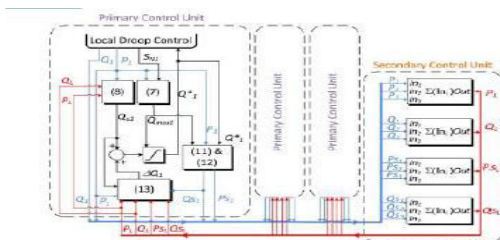


Fig. 5. Block diagram of developed reactive power sharing algorithm in real-time implementation.

The last reference estimations of reactive powers are figured, when the all are satisfied furthermore, the exchanged information amongst PCUs and SCU don't change in next converter exchanging period. Moreover, the steady state of reactive power partaking in MG is gotten when the signals from controllers in internal control circles are built up. This procedure may take a couple of hundred milliseconds, depending on the quantity of RES

### IV. FUZZY LOGIC

Fuzzy Logic is about the relative significance of accuracy: How essential is it to be precisely right when an unpleasant answer will do? You can utilize Fuzzy Logic Toolbox programming with Matlab specialized figuring programming as an instrument for taking care of issues with fuzzy logic controller. Fuzzy logic controller is an interesting region of examination in light of the fact that it benefits an occupation of exchanging off in the middle of criticalness and accuracy something that people have been overseeing for quite a

while as shown in Fig.6. In this sense, fuzzy rationale is both old and new on the grounds that, in spite of the fact that the present day and efficient art of fuzzy rationale is still youthful, the idea of fuzzy rationale depends on age-old aptitudes of human think in

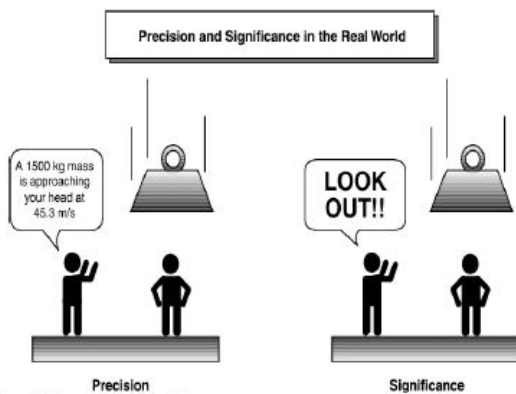


Fig.6. fuzzy description.

## A. Why use Fuzzy Logic

Fuzzy rationale is an advantageous approach to outline data space to a yield space.

Mapping info to yield is the beginning stage for everything. Consider the accompanying samples:

- With data about how great your administration was at an eatery, a fuzzy rationale system can let you know what the tip ought to be.
- With your particular of how hot you need the water, a fuzzy inference system can alter the spigot valve to the right setting.
- With data about how far away the subject of your photo is, a fuzzy inference system can center the lens for you.
- With data about how quick the auto is going and how hard the engine is
- 

- functioning, a fuzzy logic system can change gears for you.

To decide the suitable measure of tip requires mapping inputs to the proper yields. Between the info and the yield, the former figure demonstrates a discovery that can contain any number of things: fuzzy systems, direct systems, master systems, neural systems, differential mathematical statements, introduced multidimensional lookup tables, or even a profound consultant, just to give some examples of the conceivable alternatives. Obviously the rundown could continue forever. Of the many approaches to make the discovery work, things being what they are fuzzy is frequently the absolute best way. Why ought to that be? As LotfiZadeh, who should be considered be the father of fuzzy rationale, once commented: "For each situation you can assemble the same item without fuzzy rationale, however fuzzy is speedier and less expensive.". At the point when don't utilize Fuzzy logic Fuzzy logic is not a cure-all. At the point when would it be advisable for you to not utilize fuzzy rationale? The most secure articulation is the first made in this presentation: fuzzy rationale is an advantageous approach to delineate data space to a output space. In the event that you discover it's not helpful, take a stab at something else. In the event that a more straightforward arrangement as of now exists, use it. Fuzzy rationale is the codification of sound judgment—use judgment skills when you actualize it and you will presumably settle on the right choice. Numerous controllers, for instance,



make a fine showing without utilizing fuzzy logic.

- On the other hand, in the event that you set aside an ideal opportunity to
- get comfortable with fuzzy rationale, you'll see it can be a capable apparatus for managing rapidly and proficiently with imprecision and nonlinearity.
- what can fuzzy rationale tool stash programming do?
- You can make and alter fuzzy derivation systems with Fuzzy Logic Toolbox programming. You can make these systems utilizing graphical devices or order line capacities, or you can create them consequently utilizing either grouping or versatile neuro- fuzzy systems.
- In the event that you have entry to Simulink programming, you can without much of a stretch test your fuzzy system in a piece graph recreation environment.
- The tool stash likewise gives you a chance to run your own particular stand-alone C programs specifically. This is made conceivable by a stand-alone Fuzzy Inference Engine that peruses the fuzzy systems spared from a matlab session. You can tweak the stand-alone motor to incorporate fuzzy derivation with your own particular code. All gave code is ansi consistent.

- Due to the incorporated way of the matlab environment, you can make your own particular devices to tweak the tool compartment or saddle it with another tool compartment, for example, the Control System Toolbox, Neural Network Toolbox, or Optimization Toolbox programming.

## **B. Fuzzy Logic Tool box**

The Fuzzy Logic Toolbox expands the MATLAB specialized registering environment with devices for outlining systems in view of fuzzy rationale. Graphical unit interfaces (GUIs) guide you through the progressions of fuzzy induction system outline. Capacities are accommodated numerous basic fuzzy rational techniques, including fuzzy grouping and versatile neuro fuzzy learning. The tool compartment gives you a chance to model complex sytem practices utilizing basic rationale standards and after that actualizes these tenets in a fuzzy deduction system. You can utilize the tool kit as a standalone fuzzy surmising motor. Then again, you can utilize fuzzy deduction hinders in simulink and recreate the fuzzy susyems inside of a far reaching model of the whole element system. working with the fuzzy rationale tool compartment: The Fuzzy Logic Toolbox gives GUIs to give you a chance to perform traditional fuzzy system improvement and example acknowledgment. Utilizing the tool kit, you can create and examine fuzzy induction systems, create versatile neuro fuzzy surmising systems, and perform fuzzy grouping. Likewise, the tool stash gives a fuzzy controller piece that you can use in

Simulink to display and mimic a fuzzy rationale control system. From Simulink, you can create C code for use in implanted applications that incorporate fuzzy rationale.

### C. Building a Fuzzy Inference System

Fuzzy surmising is a strategy that deciphers the qualities in the data vector and, taking into account client characterized principles, allocates qualities to the output vector. Utilizing the GUI editors and viewers in the Fuzzy Logic Toolbox, you can fabricate the guidelines set, characterize the participation capacities, and investigate the conduct of a fuzzy inference system (FIS). The accompanying editors and viewers as shown in Fig.7

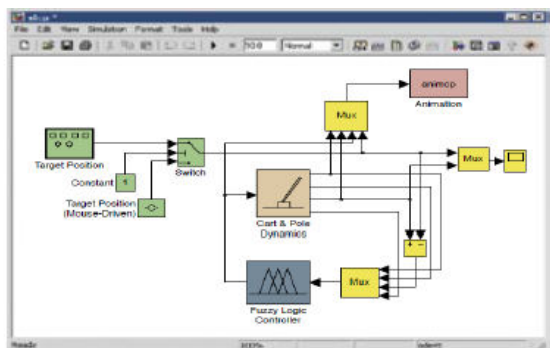


Fig.7.Fuzzy Inference System.

### Key Features:

- Specialized GUIs for building fuzzy inference systems and viewing and analyzing results
- Membership functions for creating fuzzy inference systems
- Support for AND, OR, and NOT logic in user-defined rules
- Standard Mamdani and Sugeno-type fuzzy inference systems

- Automated membership function shaping through neuro adaptive and fuzzy clustering learning techniques
- Ability to embed a fuzzy inference system in a Simulink model.
- Ability to generate embeddable C code or stand-alone executable fuzzy inference engines.

In this area we'll be building a straightforward tipping sample utilizing the graphical unit interface (GUI) apparatuses gave by the Fuzzy Logic Toolbox. In spite of the fact that it's conceivable to utilize the Fuzzy Logic Toolbox by working entirely from the summon line, when all is said in done it's much simpler to construct a system graphically. There are five essential GUI apparatuses for building, altering, and watching fuzzy induction systems in the Fuzzy Logic Toolbox. The Fuzzy Inference System or FIS Editor, the Membership Function Editor, the Rule Editor, the Rule Viewer, and the Surface Viewer. These GUIs are progressively connected, in that progressions you make to the FIS utilizing one of them can influence what you see on any of the other open GUIs. You can have any or every one of them open for any given system. These are shown in Fig.8.

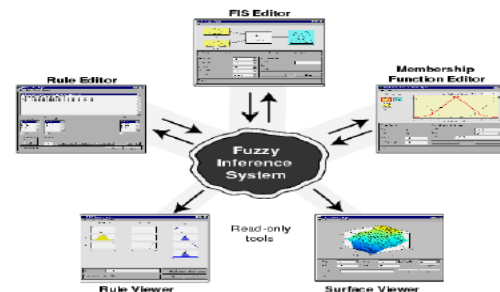


Fig.8.The Primary GUI Tools of the Fuzzy Logic Toolbox.

The FIS Editor handles the abnormal state issues for the system: what number information and yield variables? What are their names? The Fuzzy Logic Toolbox doesn't restrict the quantity of inputs. On the other hand, the quantity of inputs may be restricted by the accessible memory of your machine. In the event that the quantity of inputs is too huge, or the quantity of enrollment capacities is too huge, then it might likewise be hard to investigate the FIS utilizing the other GUI apparatuses. The Membership Function Editor is utilized to characterize the states of all the enrollment capacities connected with every variable. The Rule Editor is for altering the rundown of principles that characterizes the conduct of the system.

## V. SIMULATION RESULTS

### A. Classical Droop Control

#### 1. Active Powers:

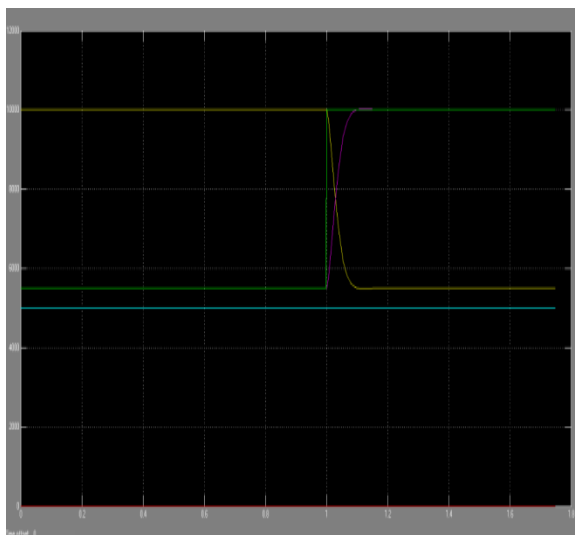


Fig.9.

#### 2. Reactive Powers:

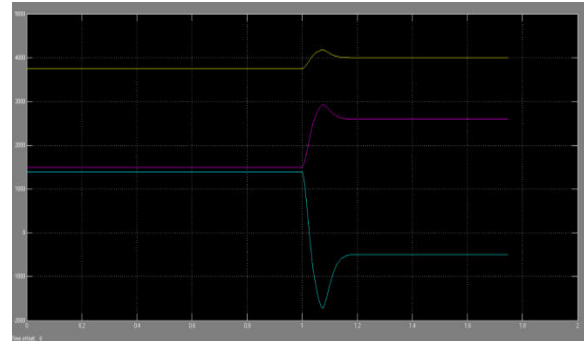


Fig.10. 3.

#### Apparent Powers:

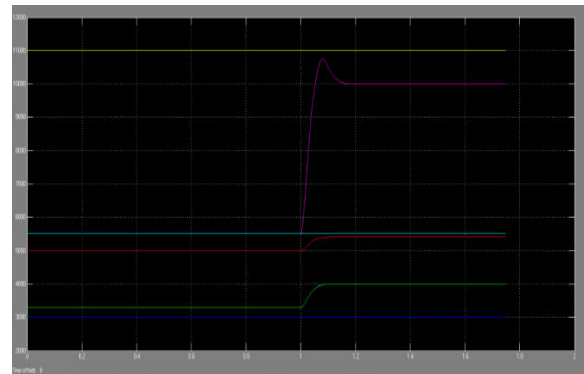


Fig.11.

Figs. 9 to 11 Powers of converters in islanded MG without reactive power management with step change of maximum active power from RESs: p1, p2, p3, pstorage, converters active powers; p\_mppt1, p\_mppt2, p\_mppt3, maximum active powers calculated from MPPT; q1, q2, q3, converters reactive powers; S1, S2, S3, converters apparent powers; SN1, SN2, SN3, converters nominal apparent powers.

## B. Equal Reactive Power Sharing

### 1. Active Powers:

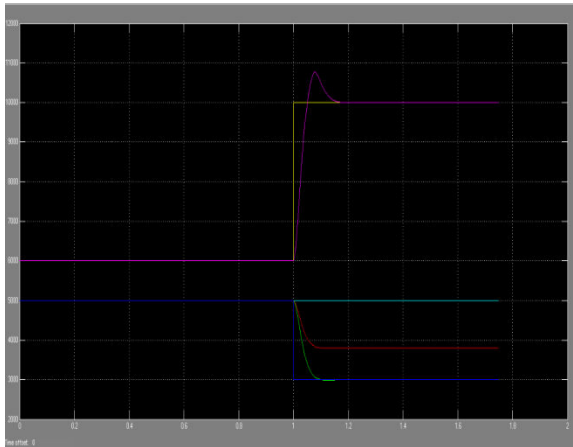
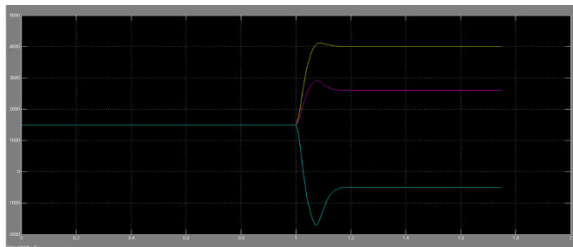


Fig.12.

### 2. Reactive Powers:



### 3. Apparent Powers:

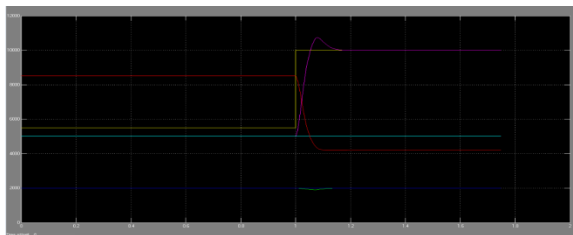


Fig.14.

Figs.12 to 14 Powers of converters in islanded MG with ERPS with step change of maximum active power from RESs: p1, p2, p3, pstorage, converters active powers; p\_mppt1, p\_mppt2, p\_mppt3, maximum

active powers calculated from MPPT; q1, q2, q3, converters reactive powers; S1, S2, S3, converters apparent powers; and SN1, SN2, SN3, converters nominal apparent powers.

## C. Proportional Power Sharing

### 1. Active Powers:

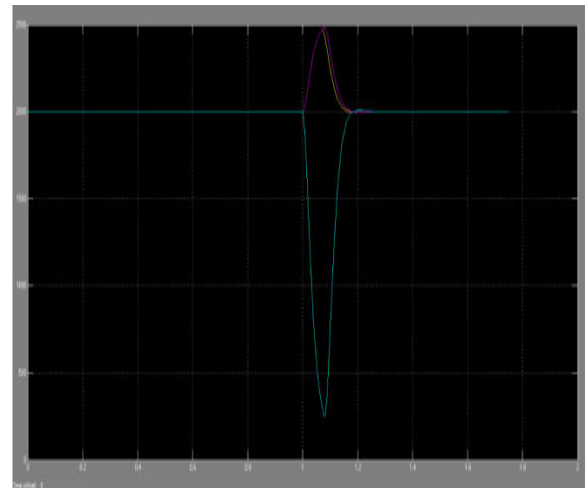


Fig.15.

### 2. Reactive Powers:

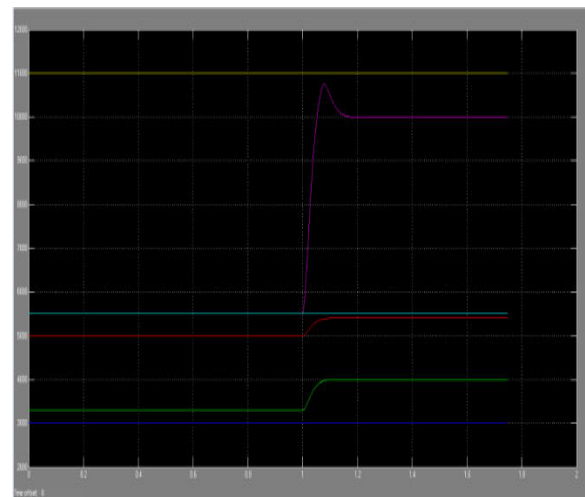
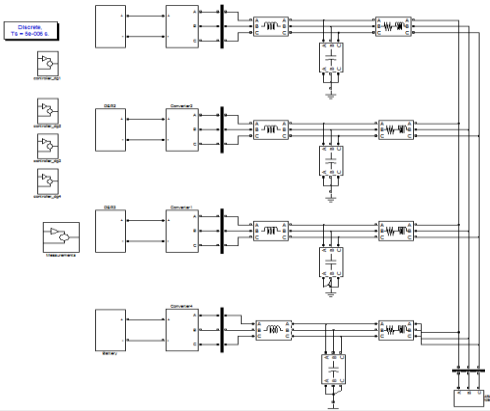
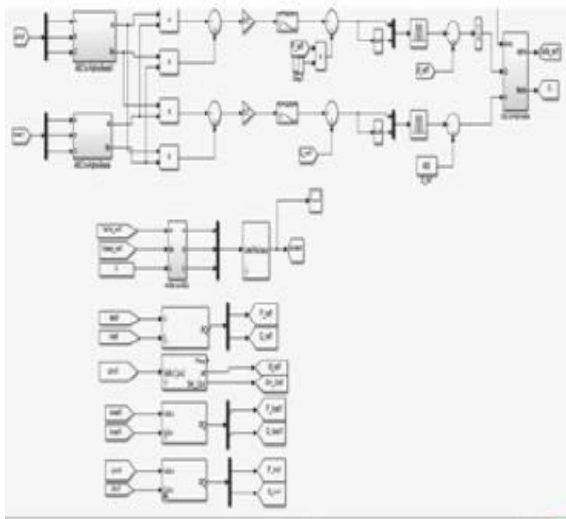


Fig.16.

## B. Proposed Method Results



Sumlink Block Diagram.



Block scheme of simulation model.

TABLE I: Results comparisons of Existing PI Controller & Proposed Fuzzy Logic Controller

S.No.	Conreoller	THD(%)
1.	FLC	35.29
2.	PI	51.30

## VI. CONCLUSION

MG is the development system for RES mix with own control structure. Normally the progressive control is actualized with hang control in essential level. In islanded mode of operation there is the need to oversee reactive power sharing furthermore, permit RESs work with most extreme active power. Thus, the new reactive power sharing calculation was proposed in this paper, taking into account the examination of power sharing between converters in MG. The novel arrangement keeps the reactive power flow and detachment or harm of any converter in MG. Additionally, it permits to converters operation with MPPT, bringing about better abuse of every RES and keeping evident power of every unit underneath ostensible level as far as might be feasible. As a result of short exchanging time of power devices converters in RES, the calculation was produced for usage in progressive control structure, giving parallel estimations in each PCU. Reproduction examination was performed, where the three arrangements of power control in islanded MG were thought about what affirms the right operation of created calculation and demonstrates the upside of relative power sharing over others arrangement exhibited in writing.

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