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Application of Enhanced Sine Cosine Algorithm for Optimal Allocation of PV- DG and DSTATCOM in Distribution Systems

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Abstract

The allocation and optimization of renewable energy and shunt compensators remains a challenging task to enhance the performance of system efficiently. This paper suggests a new methodology to determine the optimal placement and ratings of the Photovoltaic based distributed generator (PV- DG) and Distribution Static compensator (DSTATCOM) in radial distribution systems. An Enhanced Sine cosine algorithm (ESCA) is applied to solve the allocation problem of the PV- DG and DSTATCOM. The ESCA is proposed for improvement the searching capabilities of the conventional Sine Cosine Algorithm (SCA) by using the Levy Flight Distribution (LFD) and adaptive operator. to demonstrates effectiveness of the proposed algorithm, it has been tested on IEEE 33 and IEEE 69 bus systems for loss minimization by PV-DG and the obtained results are compared with other algorithm. The ESCA is applied for optimal inclusion assigning the PV- DG and DSTATCOM for a multi-objective function which comprises of three objective functions including the power loss reduction, voltage profile improvement and voltage stability enhancement. The outcomes reveal to that optimal inclusion of the PV- DG and DSTATCOM can enhance the performance of the system considerably. In addition of that the proposed algorithm is superior for solving the allocation problem compared with the state-of-the-arts algorithms.

Keywords: PV, Distribution System, Power Losses, Renewable Energy, Voltage Profiles.

1. Introduction

The radial distribution system (RDS) comprise various loads, thus, RDS has pauper power quality in terms of system power losses, voltage coil, and system stability [1]. Reactive power restitution is required to get better power quality in RDS. Improving power quality in some cases, hence power resources need to be included in RDS to achieve rise power quality [2].

At present, the bulk of power generation is produced by generators based on fossil fuels such as gas, and small turbines [3]. Renewable energy based DG [4] Such as wind turbines



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(WT), (PV) photovoltaic and small hydroelectric generators besides energy efficiency. [5] It has been recognized worldwide as an effective pathway to avoid the associated with traditional energy problems sources. Besides, the concept of small grid is also seen as a promising solution for optimum utilization of energy resources[6] and to enhance the flexibility of power distribution systems [7].

Photovoltaic energy based on photovoltaic a new renewable energy is resource that has been widely integrated into distribution networks to achieve many benefits to enhance the environmental, technical and The PV modules economic benefits [8] [9]. convert the solar radiation into DC energy by its solar cells and then an inverter is used to invert the DC voltage into AC voltage. There are two options for connecting the PV system, first installation is to connect the the photovoltaic power to the electrical grid which is known as the PV system to the grid, and the other connection is regulated by feeding an independent system known as the off-grid PV system. Several improvements have been used to set the optimum capacity for PV modules such as; Genetic algorithm [10, 11], artificial colony [12], grasshopper optimization bee algorithm [13], moth flame optimizer [14], lightning attachment procedure optimization [15], backtracking search optimization [16] and ant lion optimization [17].

SCA technology is a new improvement technology he introduced [18]. The prime deficiency of the SCA is her stagnant and native idealism. An amended version of SCA has been proposed to enhance the exploration and exploitation of traditional SCA. The ISCA relies on Levy's flight distribution and adaptive operators to enhance the search abilities of the primary SCA.

This paper proposes a new methodology to the renewable energy planning solve optimization problem based on the Enhanced sine Cosine algorithm (ESCA), in addition, the paper effects of combine DSTATCOM and PV modules into the distribution network. The proposed algorithm was tested on 33 and 69 vector radial distribution systems. The studied objective function includes minimizing power minimizing losses. voltage deviations and improving voltage stability. The results obtained via the proposed algorithm were compared with other results to highlight its benefits in reducing the total energy loss.

2. Problem Formulation

In the case of inclusion of the hybrid PV-DG and DSTATCOM as depicted. Eq. (1-3) is used to obtain the power flow solution in the RDS with inclusion PV units and DSTATCOM shown in Fig. 1.

$$\begin{split} P_{n+1} &= P_n - P_{L,n+1} - R_{n,n+1} \left(\frac{P_n^2 + j Q_n^2}{|V_n|^2} \right) + P_{PV} \\ Q_{n+1} &= Q_n - Q_{L,n+1} - X_{n,n+1} \left(\frac{P_n^2 + j Q_n^2}{|V_n|^2} \right) + Q_{DSTAT} \end{split}$$



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Fig.1 Schematic graph of system with PV and DSTATCOM

where, $X_{n,n+1}$ and $R_{n,n+1}$ are reactance and resistance of the line between buses h and n+1, respectively. Q_n and P_n are the real and reactive powers flows, respectively. The active and reactive power losses are given as follows:

$$P_{loss(n,n+1)} = R_{n,n+1} \left(\frac{P_n^2 + jQ_n^2}{|V_n|^2} \right)$$
(3)

The voltage stability index can be found as follows.

$$VSI_{(n+1)} = |V_n|^4 - 4(P_{mn+1}X_n - (4))$$
$$Q_{n+1}R_n)^2 - 4(P_{mn+1}X_n + Q_{n+1}R_n)|V_n|^2$$

where, $VSI_{(n+1)}$ is the voltage stability index, voltage deviations of RDS can be found as follows:

$$VD = \sum_{g=1}^{n} |V_n - 1|$$
 (5)

where, n is number of system nodules.

3. Objective Function

In this paper, the purpose of inclusive PV and DSTATCOM is to reduce power losses, improve system stability, and improve the voltage profile. So, the objective function is jO_{ij} subedit as follows:

$$\phi = \lambda_1 \phi_1 + \lambda_2 \phi_2 + \lambda_3 \phi_3 \tag{6}$$

where, λ_1 , λ_2 and λ_3 are weighting factors. **Cohec**tion of the weight factors assigned to all effects must add up to one as:

$$|\lambda_1| + |\lambda_2| + |\lambda_3| = 1$$
(7)

 $Ø_1$ is the first objective of the multi objective assignment which total active power losses decrease and it can be found as follows:

$$\phi_1 = \frac{P_{T,loss}}{\left(P_{T,loss}\right)_{base}} \tag{8}$$

where, $P_{T,loss}$ are the total active power losses in system. The base bed icon ticks the basic state of the network (without PV and DSTATCOMs). $Ø_2$ exemplify the improvement the voltage profile, which is persuaded by decrease the sum of the voltage deviations in RDS and can be given as follows:

$$\phi_2 = \frac{VD}{(VD)_{base}} \tag{9}$$

where, $Ø_3$ The improvement of the voltage stability that can be achieved by improving the voltage stability index (VSI) is represented as follows:

$$\phi_3 = \frac{1}{\sum_{i=1}^{nb} |VSI(i)|_{base}}$$

4. System Constraints

The system constraints are classified as follows:



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4.1 Equality Constraints

Equality constraints contain flows of active and reactive forces which can be given as follows:

$$P_{s} + \sum_{i=1}^{np} P_{PV} = \sum_{h=1}^{n} P_{D}(h) + \sum_{j=1}^{nl} P_{loss}(j)$$
(11)
$$Q_{s} + \sum_{i=1}^{nc} Q_{DSTATcom}(i) = \sum_{h=1}^{n} Q_{D}(h) + \sum_{i=1}^{nl} Q_{loss}(j)$$
(12)

where, P_s and Q_s It is the active and reactive powers supply at the substation, respectively. P_D and Q_D are Active and reactive load, respectively. nl is the number of transmission lines in RDS. nc is the number of DSTATCOM. np is the number of PV modules.

4.2 Inequality Constraints

$$V_{min} \le V_i \le V_{max} \tag{1}$$

$$\sum_{i=1}^{nc} Q_{DSTATCOM}(i) \le \sum_{i=1}^{n} Q_{D}(i) \qquad \begin{array}{c} (\\ 1\\ 4 \end{array}$$

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where, V_{min} and V_{max} are the lower and upper voltage limits. P_D and Q_D are is the active and reactive loads. $Q_{DSTATCOM}$ Reactive force is injected by DSTATCOM. P_{PV} is injected reactive power by PV modules.

5. Optimization Algorithm

SCA It is optimization algorithm. SCA is a population based algorithm and its combinations about the best solutions are updated based on a random process using cosine functions as shown in Fig.2 which can be described as follows [18, 19]:

X^{t+1}

$$= \begin{cases} X_i^t + y_1 \times \sin(y_2) \times \left| y_3 X_{best}^t - X_i^t \right| & (1) \\ X_i^t + y_1 \times \cos(y_2) \times \left| y_3 X_{best}^t - X_i^t \right| & (1) \end{cases}$$

where, t is the iteration X_i^{t+1} and X_i^t is the population positions at the and (t+1)th iteration at the ith dimension, respectively. X_{best}^t represents the best position. y_2, y_3 and y_4 are random numbers during range [0, 1]. y_1 exemplify an adaptive parameter that is instituted as follows:

$$y_1 = k - t \times \frac{K}{t_{max}} \tag{18}$$

where, k is a fixed value. T_{max} is The maximum number of iterations. We must dot out that Eq. (18) characterize the main

3)



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countenance of the SCA algorithm as shown in Fig.2 which shows the variability of the position of the groups around the best situation based on the size and phase angle difference of the sine and cosine functions. y_1 adjust the new criterion placement to move outwardly or inward in the best placement as shown in Fig. 3.

5.1 Enhanced Sine Cosine Algorithm (ESCA)

ESCA is based on Lévy Flight Distribution (LFD), LFD is integrated into SCA technology to foster the search ability and reconnaissance capacity of this optimization algorithm by rising the likelihood of manufacture new solutions to avoid algorithm stagnation and to avert trapping at local minimums. Levy's trip is a random operation for generating a new solution based on a random walk whose steps are captured from the Lévy distribution. The new inhabitance situation which count on a fibrous distribution can be found as follows:



Fig.2. Inhabitance movement about the best solution based on cosine.

$$X_i^{new} = X_i + \propto \bigoplus Levy(\beta) \tag{19}$$

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Fig.3. The trend of the following status on the best placement count on y_1 .

where, \propto is a passing step size parameter. \bigoplus Is the prelude of wise and hitting β represents the parameter of the lévy flight distribution. The step size can be calculated as follows:

$$\propto \bigoplus Levy(\beta) \sim 0.01 \frac{W}{|v|^{1/\beta}} (X_i^t - X_{best}^t)$$
(20)

Where, u and v are usually variables produced by a normal distribution where,

$$w \sim n(0, \phi_u^2), v \sim n(0, \phi_v^2)$$
 (21)

where, Γ is the criterion gamma function and $0 \le \beta \le 2$. To foster the utilization of SCA the best search agent is updated by using changing band width as follows:

$$X_{best}^{new} = X_{best}^t \pm y_5 \times K_w \tag{23}$$

where, y_5 is a random number in [0, 1]. K_w is a variable bandwidth decreases dynamically as:

$$K_{w} = K_{max} e^{(E \times t)}$$
(24)
$$E = \left(\frac{ln\left(\frac{K_{min}}{K_{max}}\right)}{T_{max}}\right)$$
(25)



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where, K_{max} and K_{min} are the upper and lower sect width limits.t is the current iteration and T_{max} is the maximum number of iterations.

6. Simulation Results

In order to determine the proposed SCA features and the enhanced SCA algorithm and examine their performance, two radial distribution systems were selected IEEE 33 and IEEE 69-bus system. The load model for distribution systems is assumed to be a static power load [20]. The line diagram of a system considered is shown in Fig. 4 and Fig. 5. The proposed algorithm is a code using MATLAB 2019b and simulations are present on a Dell computer of an intel core TM I7 processor with a frequency of 3.20 GHz and 32.0 GB of RAM. Back/forward sweep algorithm [21]- [22], its affinity is strong and assured [20], Solve calculations of energy flow. Specifications parameters and primary power flow results without any RESs are shown in Table 1 and Table 2.

 Table 1. System specification and initial power flow.

y 1	1		
Item	Value	Value	
System Specifications:			
NB	33	69	
Npr	32	68	
Vsys (kV)	12.66	12.66	
Base MVA	100	100	
S _{Load} (MVA)	3.715 + j2.300	3.802 + j2.694	
P _{Total_{loss} (kW)}	210.84	225	
Q _{Total_{loss}} (kVar)	143.022	102.198	
V _{min} (p.u) @ bus	0.90378, 18	0.90919, 65	







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Fig 5. Single line diagram of IEEE 33 bus system

Table	2.	Input	parameters	used in	numerical	simulations.
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1 1	
Item	Set value(s)
SCA-ESCA parameters:	
Niter,max	100
Npop	50
Nruns	50
System inequality constraints:	
Bus voltage limits (p.u.)	±5%*
PV size limits (MVA)	$0 \leq SPV \leq 3$
PV Power Factor limits [24]	$1 \le \text{PFPV} \le 1$

7. The First Case Study 33 Bus System.

The first taste system over the proposed ESCA is the 33-bus system. Its total load is 3720 kW and 2300 kVA at voltage level of 12.66 kV. Table 3,4 describes the effects of fixation of different types and numbers of PV on system performance. The superiority of the ESCA has been demonstrated in selecting the optimal sites and size of the photovoltaic compared to those obtained. are shown in Table 5,6,7.Significant reduction in active energy loss was enhanced for both PV. In addition, a marked improvement in the voltage profile and system stability was achieved, as shown in Fig.6 and Fig.7, respectively. In the first method, bus number 6 has been suggested as the optimal location for PV. The optimum size for PV is 2590.2 kW. The energy power loss resulting from the proposed technology has decreased to 111.02 kW.

In the second method, the integration of multiple PV-DGs (**two and three modules**) is considered, and their effects are investigated. In the case of two PV-DGs, buses 13 and 30 were selected as ideal sites for PV-DGs integration with capacities of 851.4817 kW and 1154 kW respectively. On the other hand, the optimal locations for three PV-DGs are buses 30, 13 and 24 and the PV capacities are 1053.5, 802



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and 1091.3 kW respectively. It is noteworthy that the active power loss was significantly

reduced to 87.165 kW and 72.785 kW by two PV-DGs and three PV-DGs, respectively.

Items	Without			With	n PV		
	-PV	One PV		Two PV		Three PV	
		ESCA	SCA	ESCA	SCA	ESCA	SCA
Total	210.98	111.02	111.016	87.165 87.343		72.785	78.928
losses							
(kW)							
Minimum	0.90378	0.94237	0.94231	0.96839 @	0.96626 @	0.96867	0.97711
voltage	@ bus	@ bus	@ bus	bus 33	bus 33	@ bus	@ bus
	18	18	18			33	33
Maximum	0.99703	0.99858	0.99858	0.99826 @	0.99822 @	0.99882	0.99910
voltage	@ bus	@ bus	@ bus	bus 2	bus 2	@ bus	@ bus
	2	2	2			2	2
PV size in	-	2590.2	2585.7	851.4817(13)	832.4591(13),	1053.5	1100.8
kW		(6)	(6)	,	1096 (30)	(30),	(24),
(Location)				1154 (30)		802 (13)	1195
						,	(12),
						1091.3	1151.0
						(24)	(30)
VSI	25.5401	28.5219	28.5166	29.3803	29.2442	29.6167	30.4819
VD (p.u)	1.8044	0.9237	0.9252	0.6786	0.7156	0.6167	0.3865

 Table 3. The results of installing of PV units in the first system.

Table 4. Results of optimized allocation of PV units in 33 bus

Withou	t -PV						With Multi-Objective Function								
Items															
				ES	CA					S	CA				
			PV1		PV2		PV3		PV1		PV2		PV3		
Total	210.	98	111.	012	87.252		72.885		111.	016	87.56	60	76.6	64	
losses															
(kW)															
Minimum	0.90	378	0.94	237	0.9642	5	0.96772	2	0.94	231	0.965	533	0.95	496	@
voltage	@	bus	@	bus	@ bus	18	@ bus	33	@	bus	@	bus	bus	18	
	18		18						18		18				



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Maximum	0.99703	0.99858	0.99830	0.99882	0.99858	0.99835	0.99857 @
voltage	@ bus	@ bus	@ bus 2	@ bus 2	@ bus	@ bus 2	bus 2
	2	2			2		
PV size in	-	2590.2	1104.4(30)	11091	2585.7	947.3237	795.8191(11),
kW		(6)	,	(24),	(6)	(12),	831 (31),
(Location)			957 (12)	838 (13),		1215 (30)	896.2417 (24)
				1006.2(30)			
VSI (p.u)	25.5401	28.5219	29.7753	29.6395	28.5166	29.6288	29.0059
VD (p.u)	1.8044	0.9237	0.5720	0.6106	0.9252	0.6126	0.7840

 Table 5. A comparative results for incorporating Single PV in 33-bus system

Tachniqua	Without	GA	PSOPC[24]	EVPSO[24]	AEPSO	ADPSO	DAPSO	Analytical	GA
reennique	vv mout	[23]	15010[24]	EVI 50[24]	[24]	[24]	[24]	[25]	[26]
$P_{loss}(KW)$	210.98	105.481	136.75	140.19	131.43	129.53	127.17	111.24	132.64
Location	-	6	15	11	14	13	8	6	6
Size	-	2580	763	1000	1200	1210	1212	2490	2380
(kVA)									
Tachniqua	BSOA	FSCA							
rechnique	[16]	ESCA							
$P_{loss}(KW)$	118.12	111.02							
Location	8	6							
Size	1857 5	2500.2							
(kVA)	1037.3	2390.2							

Table 6. A comparative results for incorporating Two PV in 33-bus system

Technique	Without	[28]MINLP	Exhaustive	EA-	EA <mark>[29]</mark>	Hybrid[30]	PSO <mark>[30</mark>]	[31]IA	ESCA
	210.00	0.5.1.(5			05 152	07.000	0.5.1.50	07.550	0
$P_{loss}(KW)$	210.98	87.167	87.17	87.17	87.172	87.280	87.170	87.550	87.165
Location		13	13	13	13	13	13	12	13
Location	-	30	30	30	30	30	30	30	30
Size	-	850,	852,	852,	844,	830,	850,	1020,	851.4817,
(kVA)		1150	1158	1158	1149	1110	1160	1020,	1154

Table	7.	A compar	ative result	s for	r incorporating	g Three	PV	in 33	3-bus	system
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Technique	Without	[28]MINLP	Exhaustive OPF [29]	EA- OPF[29]	EA[29]	Hybrid[30]	PSO[30]	IA[31]	ESCA
$P_{loss}(KW)$	210.98	105.481	136.75	140.19	131.43	129.53	127.17	111.24	132.64
Location	-	13	13	13	13	13	13	13	30



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		24	24	24	24	24	24	24	13
		30	30	30	30	30	30	30	24
	-	800,	802,	802,	798,	790,	770,	900,	1053.5
Size		1090,	1091,	1091,	1099,	1070,	1090,	900,	,
(kVA)		1050	1054,	1054	1050	1010	1070	900	802,
									1091.3

8. The Second Case Study 69 Bus System.

In this case, optimization results are with ESCA mono obtained and multimodulated PV summarized in Table 8. The voltages and VSI voltages profiles are also illustrated in Fig.8 and Fig.9, respectively. The branch active energy loss profile is shown in Table 9. In the first method, a renewable energy integration is considered as (PV), bus 61 was nominated as the best location for the installation of the 1,872.7 kW PV array. The optimized layout of the PV module greatly reduces the active power loss, improves the voltage profile and the system stability so that the minimum bus voltage is 0.96829 p.u and VSI is 64.621 p.u.

In the second method, the optimal planning of renewable energy is examined taking into account the integration of multiple renewable energy. In the case of the two PV DGs, bus number 18 and 61 were nominated as the best locations, and the optimum capacity of the PV DGs is 531.26 kW and 1781 kW, respectively. It is noted that the

input of two PV DGs successfully participates in reducing the active power losses to 71.675 kW, and increasing the minimum voltage point to 0.97893 p.u. And VSI to 66.021p.u. Where the active power loss is reduced to 69.449 kW with three PV DGs power stations. Moreover, the system bus voltage profile was significantly improved by a precise uniform pattern as in Fig.8, which was confirmed by improvement in the minimum value of bus voltages before and after connection. The best value of power losses (for a moment, 83,224 kW with one PV) obtained by the proposed algorithm is lower than the best values shown in previous works. This reveals the efficiency algorithm developed over other of the methods to solve the problem of optimal allocation of renewable energy in distribution Table networks. 10,11,12. Comparative results of incorporating PV into a 69 bus system. Figures. 10, 11, 12, Figures 13, 14, 15. From the affinity graph, it can be seen that the objective value (total energy loss) converges rapidly in ESCA.

Table 8. The results of installing of PV units in the second system.

Items							
	PV	One PV		Two PV		Three PV	
		ESCA	SCA	ESCA	SCA	ESCA	SCA



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Total	225	83.222	83.231	71.675	72.201	69.484	70.757
losses							
(kW)							
Minimum	0.90919 @	0.96829 @	0.96819	0.97893 @	0.98169	0.97938	0.97478
voltage	bus 65	bus 27	@ bus 27	bus 65	@ bus	@ bus	@ bus
					65	65	65
Maximum	0.99997 @	0.99997 @	0.99997	0.99997 @	0.99998	0.99998	0.99998
voltage	bus 2	bus 2	@ bus 2	bus 2	@ bus	@ bus	@ bus
					2	2	2
PV size in	-	1872.7 (61)	1856.7	531.2598	1856.1	596.0304	1601.9
kW			(61)	(18),	(61),	(11),	(61),
(Location)				1781 (61)	566 (16)	381 (18),	420 (19),
						1719.0	465.0150
						(61)	(9)
VSI (p.u)	61.2181	64.6212	64.5925	66.0295	66.3084	66.3258	65.8222
<i>VD</i> (p.u)	1.8374	0.8729	0.8805	0.5002	0.4280	0.4241	0.5549

Table 9. Results of optimal allocation of PV-DGs.

Wit	thout -PV	With Multi-Objective Function					
Items							
			ESCA	_		SCA	
		PV1	PV2	PV3	PV1	PV2	PV3
Total losses	225	89.230	77.605	74.412	89.393	79.677	77.635
(kW)							
Minimum	0.90919	0.97072	0.99087	0.98810	0.97075	0.99211	0.99179
voltage	@ bus 65	@ bus	@ bus 65	@ bus	@ bus	@ bus 65	@ bus
		27		65	27		65
Maximum	0.99997	0.99997	1.00118	0.99998	0.99997	1.00298	0.99998
voltage	@ bus 2	@ bus 2	@ bus 17	@ bus 2	@ bus	@ bus 15	@ bus 2
					2		
PV size in	-	2293.4	743.7399	576.8192	2299.1	827.4227	2128.2
kW		(61)	(18),	(54),	(61)	(16),	(61),
(Location)			2096 (61)	1900 (61),		2119 (61)	716 (16),
				601.1664			705.0186
				(22)			(3)
VSI (p.u)	61.2181	65.3700	67.2296	67.1408	65.3645	66.9367	67.1311



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VD (p.u) 1.83 [°]	74 0.6766	0.2002	0.2150	0.6780	0.2672	0.2170	

Table 10. A comparative results for incorporating Single PV in 69-bus system

Tachniqua	Without	MINI D[20]	Exhaustive	EA-		Hybrid[30]	PSO[30]	GA	
Technique			[29]OPF	OPF[29]				[10]	UA [
$P_{loss}(KW)$	225	83.222	83.23	83.23	83.323	83.222	83.372	83.222	132.6
Location	-	61	61	61	61	61	61	61	61
Size	-	1870	1870	1870	1872	1810	1870	1794	1819.6
(kVA)									
Technique	ESCA								
$P_{loss}(KW)$	83.222								
Location	61								
Size	1972 7								
(kVA)	10/2./								

Table 11. A comparative results for incorporating Two PV in 69-bus system

	1		1	0		5			
Tachniqua	Without	MINLP[28]	GA [26]	CSA [34]	SGA	PSO	MTLBO	GA	FSCA
rechnique					[34]	[34]	[32]	[10]	LSCA
$P_{loss}(KW)$	225	71.693	71.7912	76.4	82.9	78.8	71.776	84.233	71.675
Location		17	61	22	17	14	17	1	18
Location	-	61	11	61	61	62	61	62	61
Circ	-	510,	1777,	600,	1000,	700,	519.705,	6,	531.
		1780	555	2100	2400	2100	1732.004	1794	2598,
(K V A)									1781

Table 12. A comparative	e results	for incorporating	Three PV in	n 69-bus system
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Tachniqua	Without	EA[29]	MTLBO[32]	KHA	Hybrid[30]	PSO	ESCA
Technique				[35]		[34]	
$P_{loss}(KW)$	225	69.62	69.539	69.56	69.52	69.541	69.484
		11	11	12	11	11	11
Location	-	18	18	22	17	17	18
		61	61	61	62	61	61
Size		467,	493,	496,	510,	460,	596.0304,
(kVA)	-	380,	378,	311,	380,	440,	381,
		1795	1672	1735	1670	1700	1719.0



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Fig .6. Voltage profile of the 33 bus system.



Fig .7. Voltage stability index of the 33 bus system.





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Fig .9. Voltage Stability index of the 69 bus system.



Fig .10. Change of total power loss single PV with iterations for the 33-bus system .



Fig .11. Change of total power loss two PV with iterations for the 33-bus system .



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Fig .12. Change of total power loss three PV with iterations for the 33-bus system.







Fig .14. Change of total power loss two PV with iterations for the 69-bus system.



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Fig .15. Change of total power loss three PV with iterations for the 69-bus system.

9. Optimal Integral of PV-DGs Along with DSTATCOMs

In this case, **PV-DGs** and DSTATCOMs are inserted into the IEEE 33 and 69 bus system. The results gained for these cases are listed in Table 13. The optimal position and classifications of the PV-DGs also and **DSTATCOMs** are qualified. Referring to Table 13, it can be evident that the active power loss has been significantly reduced with 33 bus systems include one PV with one DSTATCOMs to 47.059 kW, and two PVs with two DSTATCOMs to 20.881 kW, respectively. Judging from Table 13, it is evident that the voltage profile and system stability were greatly improved with simultaneous inclusion of DSTATCOMs and PV-DGs compared to PV inclusion only. Figure 16 and 18 shows the voltage profile of the system with the input of DSTATCOMs and PV-DGs. Figure 17 and 19 illustrates the VSI voltage deviations of the system with the introduction of PV DSTATCOMs. Referring to Table 14, it can be evident that the active power loss has decreased significantly with 69 bus systems comprising one PV with one DSTATCOMs to 14.360kW, and two PVs with two **DSTATCOMs** to 9.265kW, respectively.

Items			With Multi-Objective Function						
	Without –	ESCA		SCA					
	PV 33	Single PV &	Two PV &	Single PV &	Two PV &				
		Single	Тwo	Single	Two				
		DSTATCOM	DSTATCOM	DSTATCOM	DSTATCOM				
Total losses	210.98	58.443	28.882	64.024	30.265				
(kW)									

 Table 13. Simulation result with inclusion PV and DSTATCOM.



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Total Reactive		47.059	20.881	49.646	21.736
Loss (KVAR)					
Minimum	0.90378 @	0.95365 @ bus	0.98075 @ bus	0.94658 @ bus	0.97995 @ bus
voltage	bus 18	18	25	18	18
Maximum	0.99703 @	0.99896 @ bus	1.00382 @ bus	0.99869 @ bus	0.99918 @ bus
voltage	bus 2	2	30	2	30
PV size in kW	-	2531.7 (6)	873.7099 (13),	2188.7 (6)	743 (12),
(Location)			1192 (30)		1167 (30)
DSTATCOM	-	1256 (30)	460 (23),	1015 (29)	460 (5),
size in KVA			1077 (14)		980 (2)
(Location)					
VSI (p.u)	25.5401	29.8044	31.5515	29.1186	30.8336
VD (p.u)	1.8044	0.5738	0.1453	0.7590	0.2969

Table 14. Simulation result with inclusion PV and DSTATCOM .

			With Multi-Ob	jective Function		
Items	Without –	ESCA		SCA		
	PV 69	Single PV &	Two PV &	Single PV &	Two PV &	
		Single	Тwo	Single	Two	
		DSTATCOM	DSTATCOM	DSTATCOM	DSTATCOM	
Total losses	225	23.441	11.773	26.734	12.477	
(kW)						
Total Reactive		14.360	9.265	16.434	10.084	
Loss (KVAR)						
Minimum	0.90919 @	0.97306 @ bus	0.99427 @ bus	0.97054 @ bus	0.99313 @ bus	
voltage	bus 65	27	50	27	69	
Maximum	0.99997 @	1.00260 @ bus	1.00325 @ bus	0.99998 @ bus	0.99999 @ bus	
voltage	bus 2	62	14	2	2	
PV size in kW	-		1757.5 (61),	1.6430 (61)	380 (21),	
(Location)		1902.2 (61)	835 (13)		1636 (61)	
DSTATCOM	-	1353 (61)	1052.8 (10),	1037 (61)	538 (36),	
size in KVA			757 (56)		1430 (3)	
(Location)						
VSI (p.u)	61.2181	65.8998	67.8398	26.7343	67.3390	
VD (p.u)	1.8374	0.5617	0.0755	0.7332	0.1661	



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Fig .18. Voltage profile 69 bus system.



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Conclusion

This paper proposes a new methodology to determine the optimal sites and sizes of the DSTATCOM **PV-DG** in radial and system using Enhanced Sine distribution Cosine Algorithm (ESCA). The proposed algorithm is based on the Levy Flight Distribution (LFD) and adaptive operator. to demonstrates effectiveness of the proposed algorithm. The proposed algorithm was tested on the IEEE 33-bus and IEEE 69-bus radial distribution systems and the obtained results have been compared with other algorithms to demonstrate the efficiency and effectiveness of the proposed algorithm. The considered objective function is multi-objective function includes minimizing power losses, minimizing voltage deviations and improving voltage stability. Several studied cases are presented including optimal inclusion of the PV units for power losses only and a comprehensive comparison has been presented using other optimization techniques. addition of that the PV-DGs In and DSTATCOMs have been incorporated with considering the multi-objective function under single, two and three units of the PV-DGs and DSTATCOMs. The obtained results verified that the proposed algorithm is superior effective for assigning the optimal locations and ratings of the PV-DGs and DSTATCOMs other optimization algorithms. In addition of inclusion of the **PV-DGs** that and **DSTATCOMs** enhance the can system performance considerably especially with Three **PV-DGs** inclusion of and three DSTATCOM compared with other cases.

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